



# Course guide

## 804245 - IAVJ - Artificial Intelligence

Last modified: 26/09/2024

**Unit in charge:** Image Processing and Multimedia Technology Centre  
**Teaching unit:** 804 - CITM - Image Processing and Multimedia Technology Centre.

**Degree:** BACHELOR'S DEGREE IN VIDEO GAME DESIGN AND DEVELOPMENT (Syllabus 2014). (Compulsory subject).

**Academic year:** 2024    **ECTS Credits:** 6.0    **Languages:** Catalan, English

### LECTURER

**Coordinating lecturer:** Bejarano, Edison

**Others:** Bejarano, Edison  
Mateo, Ramon

### PRIOR SKILLS

Knowledge about graf theory and coding.

### TEACHING METHODOLOGY

During the classes, the lecturer will first present the theoretical and the problem to which we are looking for a solution. Together with the students, the lecturer will analyze existing solutions that solve the challenges of real-time applications such as video games.

The lecturer will provide source code that students can analyze and should complement and integrate into their own code for future use. After each session the teacher will pose possible improvements and challenges to the students to help and guide them in their autonomous learning hours.

### LEARNING OBJECTIVES OF THE SUBJECT

- To be able to define artificial intelligence techniques for video games.
- To be able to explain and differentiate artificial intelligence techniques.
- Understand the basics of classical artificial intelligence such as genetic algorithms and neural networks.
- Master the artificial intelligence systems most applied to the world of video games such as scripting, hierarchical state machines and rule systems.
- To become familiar with advanced navigation systems such as sectorization.
- Explore the latest concepts such as behavioral trees and planners.

### STUDY LOAD

Type	Hours	Percentage
Self study	90,0	60.00
Guided activities	12,0	8.00
Hours large group	18,0	12.00



Type	Hours	Percentage
Hours medium group	30,0	20.00

**Total learning time:** 150 h

## CONTENTS

### AI Agent navigation

**Description:**

Kinetic movement  
Map Markup  
Steering behaviors  
Coordinating movement for groups

**Full-or-part-time:** 21h 30m

Theory classes: 8h  
Self study : 13h 30m

### Pathfinding systems

**Description:**

The base of Dijkstra, A\*  
Navigation Mesh and sectorization  
Path beautification  
Common improvements on A\*

**Full-or-part-time:** 21h 30m

Theory classes: 8h  
Self study : 13h 30m

### Perception Systems

**Description:**

Simulating senses  
Level Markup techniques

**Full-or-part-time:** 11h 30m

Theory classes: 4h  
Self study : 7h 30m

### Decision making for videogames

**Description:**

Hierarchical state machines  
Rule systems  
Fuzzy logic  
Scripting

**Full-or-part-time:** 16h 30m

Theory classes: 6h  
Self study : 10h 30m



### Advanced systems for decision making

**Description:**

Sharing information with Blackboards  
SmartObjects  
Behavior Trees  
Planners

**Full-or-part-time:** 16h 30m

Theory classes: 6h

Self study : 10h 30m

### Tactic and strategic systems

**Description:**

Code Structure  
Waypoints Markup  
Tactical Pathfinding

**Full-or-part-time:** 16h 30m

Theory classes: 6h

Self study : 10h 30m

### Learning systems

**Description:**

Reinforced Learning  
Neural Networks  
Genetic Algorithms

**Full-or-part-time:** 20h 30m

Theory classes: 14h 30m

Self study : 6h

### AI game design

**Description:**

Shooters and 3rd person  
Driving  
RTS  
RPGs & Turn Based

**Full-or-part-time:** 23h 30m

Theory classes: 10h

Self study : 13h 30m



## Language Models

### Description:

Language models such as GPT(LLMs) for dialogue and scene generation.  
Generation of visual content with diffusion models and LLMs.  
Applications of generative AI in video games.

**Full-or-part-time:** 2h

Theory classes: 2h

## ACTIVITIES

### Exercises

### Description:

Deberán entregarse ejercicios planteados en clase en los que se aplique o implemente lo tratado en teoría.

- Patrullar y deambular
- Flocking
- Interfaz y conocimiento del mundo
- Máquinas de estados finitos
- Árboles de comportamiento (ladrillos de comportamiento)
- Ejercicio de aprendizaje automático (regresión del movimiento de proyectiles)
- Agentes ML I
- Agentes ML II
- Árbol de comportamiento táctico
- Laboratorios extra:
  - Introducción a Python (Instalación, entornos, librerías principales)
  - Introducción a librerías(Os,Numpy, pandas, opencv)
  - Introducción a Keras y Uso colaborativo y GPUs

**Full-or-part-time:** 34h 40m

Self study: 34h 40m

### Project

### Description:

Development of a scene with several agents using the techniques learned in class.

**Full-or-part-time:** 17h 20m

Self study: 17h 20m

## GRADING SYSTEM

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1. Participation and attitude towards learning: 10%.
2. Exercises: 50%.
  - Pathfinding and navigation labs (12%)
  - Decision making labs (16%)
  - Machine learning lab (4%)
  - Deep learning labs (12%)
  - Extra labs (6%)
3. Project: 25%.  
Development of a scene with several agents using the techniques learned in class.
4. Theoretical quizzes: 15%.
  - Perception and Navigation (6%)
    - Movement and Pathfinding
    - World interfacing and Knowledge
    - Decision Making
  - Learning and optimization (5%)
    - Machine Learning
    - Optimisation
  - Strategic AI Design (4%)
    - Strategy and Tactics
    - Designing Game AI

Failed students (except for those who qualify as NP) will have the option to take the re-evaluation exam. The grade of this exam will replace the grade of the theoretical questionnaires. In case of passing the course after the re-evaluation, the maximum final grade will be a 5.

Irregular actions that may lead to a significant variation of the grade of one or more students constitute a fraudulent performance of an evaluation act. This action entails the descriptive grade of failure and a numerical grade of 0 for the ordinary global evaluation of the course, without the right to re-evaluation.

If the teachers have indications of the use of AI tools not allowed in the evaluation tests, they can summon the students concerned to an oral test or to a meeting to verify the authorship.

## BIBLIOGRAPHY

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### Basic:

- Millington, Ian. AI for games . Third edition. Boca Raton : CRC Press, [2019]. ISBN 978-1-138-48397-2.

### Complementary:

- Géron, Aurélien. Hands-on machine learning with Scikit-Learn, Keras, and TensorFlow : concepts, tools, and techniques to build intelligent systems . Second edition. Sebastopol, CA : O'Reilly Media, Inc, September 2019. ISBN 9781492032649.
- Chollet, Francois. Deep Learning with Python. 2nd Edition. Manning, 2021.
- Lanham, Micheal. Hands-On Reinforcement Learning for Games. Packt, 2020.
- Newton, Peter L. i Feng, Jie. Unreal Engine 4 AI Programming Essentials. Packt Publishing, 2016. ISBN 978-1-78439-312-0.